

Fluctuations

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Fluctuations:

Deviations of the value of an observable from its average or, also, deviations of the actual time evolution of an observable from its average evolution in a system subject to random forces or, simply, undergoing chaotic motion.

Foundations: errors

The law of errors is the first example of a theory of fluctuations. It deals with sums of a large number N of values $\sigma_1, \dots, \sigma_N$ occurring randomly with probability $p(\sigma)$ equal for each pair of opposite values (i.e. $p(\sigma) = p(-\sigma)$), hence with 0 average. If the possible values of each σ are finitely many (and at least two) their sum can be of an order of magnitude as large as the number N , however such a large value is very improbable for large N and deviations from the average of the order of the square root of N follows the *errors law*, also called *normal law*, of Gauss

$$\text{probability}(\sum_{i=1}^N \sigma_i = x\sqrt{N} \text{ for } x \text{ within } [a, b]) = \int_a^b e^{-x^2/2D} \frac{dx}{\sqrt{2\pi D}}$$

if $D = \sum_{\sigma} \sigma^2 p(\sigma)$, up to corrections approaching 0 as $N \rightarrow \infty$, ($[a, b]$ being any finite interval).

Gauss' application was to control the errors in the determination of an asteroid orbit when observations, of its position in the sky, in excess of the minimum (three) necessary were available, [1].

The error law is universal in the sense that it holds no matter which are the values of the variables σ as long as

(1) they have finitely many possibilities, (2) probabilities $p(\sigma)$ give zero average to the "expectation" $\sum_{\sigma} \sigma p(\sigma) = 0$, (3) occurrence of any value takes place independently of occurrences of other values. The simplest application is to the sum of equally probable values $\sigma = \pm 1$.

Another important kind of fluctuations are the *Poisson's fluctuations* describing, for instance, the number of atoms in a region of volume v or the number of radioactive decays in a time interval τ : these are independent events which occur with an average number ν proportional to v or τ ; the probability that m events are actually observed is $P(m) = e^{-\nu}\nu^m/m!$. A feature of such fluctuations, also called “*rare events*”, is that the mean square deviation is equal to the mean: $\sum_{m=0}^{\infty}(m - \nu)^2 P(m) = \nu$.

Fluctuations: small and large

The probabilities of values $\sum_{i=1}^N \sigma_i$ of size of order N is called the theory of “large fluctuations”, because the $\sum_{i=1}^N \sigma_i$ considered in the errors law and often referred to as “small fluctuatoins” is comparatively much smaller, being of order \sqrt{N} .

Also large fluctuations show universal properties, but to a lesser extent. The analysis is quite simple when the sum $\sum_{i=1}^N \sigma_i$ involves two equally probable independent values $\sigma = \pm 1$: there is a function $f(s)$ such that the probability that $\sum_{i=1}^N \sigma_i = sN$ with $s \in [a, b]$ and $-1 < a < b < 1$

$$\text{probability}\left(\sum_{i=1}^N \sigma_i \in [aN, bN]\right) \sim e^{-N \max_{s \in [a, b]} f(s)}$$

in the sense that the logarithm of the ratio of the two sides divided by N approaches 0 as $N \rightarrow \infty$. It is $f(s) = \frac{1-s}{2} \log \frac{1-s}{2} + \frac{1+s}{2} \log \frac{1+s}{2} + \log 2$.

Existence of a function $f(s)$, called the “large deviations rate”, controlling the probabilities of events $sN = \sum_{i=1}^N \sigma_i$ for N large and $0 < |s| < \max |\sigma|$ is a rather general property.

Although the exponential dependence on N of the probability of large deviations is a universal feature, the large deviations rate function is not a universal function: only the property that $f(s)$ has a maximum at $s = 0$ with a second derivative D which is strictly positive is universal.

The error law is consistent with the large deviations law: this can be seen heuristically by using the large deviations law to study the probability of $\sum_{i=1}^N \sigma_i = x\sqrt{N} \in [a, b]$ and noting that to leading order in N it is $\sim e^{-\max_{[a, b]} x^2/2D}$ if $D =$ second derivative of $f(s)$ at $s = 0$ and $D > 0$, [2].

The universality properties of fluctuations, around their average, of sums of independent variables can be summarized by saying that the small fluctuations, of size $O(\sqrt{N})$, of sums of independent variables which assume finitely many values, have a universal (Gaussian) distribution controlled by a single parameter D . The latter is the second derivative at the maximum of a non

universal function $f(s)$ which controls the probability of large fluctuations. Large fluctuations have a probability which tends to zero exponentially with the number N , as long as $s \in [a, b]$ and $\min \sigma < a < b < \max \sigma$, while the small deviations probability is much larger and it only approaches 0 exponentially in \sqrt{N} .

Extensions: non zero mean and infinite square mean

The laws of errors and of large fluctuations are extended to the general case in which $\bar{\sigma} \stackrel{def}{=} \sum_{\sigma} \sigma p(\sigma) \neq 0$, e.g. when opposite values occur with unequal probabilities: simply they retain the same form provided $\sum_{i=1}^N \sigma_i$ is replaced by $\sum_{i=1}^N (\sigma_i - \bar{\sigma})$ and provided $0 < \sum_{i=1}^N (\sigma_i - \bar{\sigma})^2 p(\sigma) < +\infty$.

Further extensions apply to cases in which the variables σ_i take infinitely (denumerably or more) many values. In the previously considered cases the quantities $\sum_{i=1}^N (\sigma_i - \bar{\sigma})$ cannot exceed the interval $N [\min(\sigma - \bar{\sigma}), \max(\sigma - \bar{\sigma})]$; but in the cases in which $\max |\sigma| = +\infty$ the large deviations concern quantities $\sum_{i=1}^N (\sigma_i - \bar{\sigma})$ which can be of size of order larger than N . This implies that some care is needed in the extensions of the fluctuation laws, large or small, to such cases.

For instance suppose σ_i can take infinitely many values with probabilities $p(\sigma) = p(-\sigma)$ that decay to 0 too slowly for having $\sum_{\sigma} p_{\sigma} \sigma^2 < \infty$, and consider the special case in which $\int_s^{\infty} p(\sigma) d\sigma$ is, asymptotically for $s \rightarrow \infty$, proportional to $s^{-\alpha}$, $0 < \alpha < 2$; then the “small deviations” have size $N^{\frac{1}{\alpha}}$ (rather than $N^{\frac{1}{2}}$) in the sense that the variable $\sum_{i=1}^N \sigma_i$ is $sN^{\frac{1}{\alpha}}$ for $s \in [a, b]$ with a probability of the form $\int_a^b e^{F_{\alpha,c}(x)} dx$ and with $F_{\alpha,c}$ universal i.e., whatever the distribution of the σ is, the law depends on it only through a parameter c which plays the role of D in Gauss’ law, [2, Ch.7]. If $\alpha = 1$ then $F_{\alpha}(s) = \frac{1}{\pi} \frac{c}{c^2 + s^2}$.

The cases in which the probabilities $p(\sigma)$ are not symmetric in σ are more involved in the sense that the laws of s depend on $p(\sigma)$ through more than one parameter rather than on one only, [2]. For instance if $\alpha = 1$ and $\int_s^{\infty} p(\sigma) d\sigma$ is, asymptotically for $s \rightarrow \infty$, proportional to $s^{-\alpha}$, but $p(\sigma) = 0$ for $\sigma < 0$, then $f(s) = \frac{1}{\sqrt{2c\pi s^3}} e^{-\frac{1}{2cs}}$; this is *Smirnov’s law*.

If $\int \sigma^2 p(\sigma) = +\infty$ in general the $\sum_{i=1}^N \sigma_i$ might not admit a limit law $f(s)$, not even for the small fluctuations. This means that, even for suitable choices of α and a_N , there needs not exist a function $f(s)$ such that $N^{-\frac{1}{\alpha}} \sum_{i=1}^N (\sigma_i - a_N)$ has probability of falling in $[a, b]$ asymptotically given by $\int_a^b f(s) ds$. A necessary and sufficient condition for the existence of a limit law is, if the tails of the distribution of the single events σ are denoted

$r_+(s) = \int_s^\infty p(\sigma)d\sigma$ and $r_-(s) = \int_{-\infty}^{-s} p(\sigma)d\sigma$, that $\lim_{s \rightarrow +\infty} \frac{r_+(s)}{r_-(s)}$ exists and $\lim_{s \rightarrow +\infty} \frac{r_+(s)+r_-(s)}{r_+(ks)+r_-(ks)} = k^\alpha$ with $0 < \alpha < 2$, [2].

Brownian motion

The theory of Brownian motion deals with pollen particles (“colloid”) suspended in a viscous medium (e.g. “water”) which can be considered, although of huge size, as large molecules and, therefore, statistical mechanics applies to them.

Remarkably Einstein developed the theory without knowing the available experimental evidence, hence he could say:

It is possible that the movements to be discussed here are identical with the so-called "Brownian molecular motion", however, the information available to me regarding the latter is so lacking in precision, that I can form no judgment in the matter

and, a little later, he attributed the evidence “in the first instance” to M. Gouy rather than to the 1867 series of experimental results published by G. Cantoni who had concluded

“in fact, I think that the dancing movement of the extremely minute solid particles in a liquid, can be attributed to the different velocities that must be proper, at a given temperature, of both such solid particles and of the molecules of the liquid that hit them from every side. I do not know whether others did already attempt this way of explaining Brownian motions...”,
[3, 4, 5].

Non rectilinear motion of the suspended particles is attributed to fluctuations due to their “random” collisions with molecules. It is a random motion, at least when observed on time scales τ large compared to the time necessary to dissipate the velocity v acquired in a single collision with a molecule. The dissipation takes place because of the friction, which in turn is also due to microscopic collisions between fluid molecules.

Viscosity of the medium slows down the particles (or acts as a “thermostat” on them) and it is also a manifestation of the atomic nature of the medium: so that there should be a relation between the value of the friction coefficient and the fluctuations of the momentum exchanges due to the microscopic collisions. This led to develop, starting from Brownian motion as a paradigmatic particular case, a class of results quantitatively relating, very near equilibrium, dissipation occurring in transport phenomena and equilibrium fluctuations of suitable observables: Einstein’s theory can be regarded as a first example of *fluctuation-dissipation theorems*.

Einstein's theory

In a (“gedanken”) gas of Brownian particles a density variation $\frac{\partial \rho}{\partial x}$ generates a material flux $\rho v = D \frac{\partial \rho}{\partial x}$ and therefore a diffusion, with coefficient of diffusion D .

On the other hand the density gradient implies a osmotic pressure gradient $\frac{\partial p}{\partial x} = \beta^{-1} \frac{\partial \rho}{\partial x}$, with $\beta \stackrel{def}{=} \frac{1}{k_B T}$, by the Raoult-van t'Hoff osmotic pressure law $p = \beta^{-1} \rho$; hence it corresponds to a force in the x -direction $F = \frac{\beta^{-1}}{\rho} \frac{\partial \rho}{\partial x}$ which, in a stationary state, is balanced by the viscosity resistance implying $F = 6\pi\eta Rv$ (Stokes formula): with η = viscosity coefficient, R = radius of the particles and v their velocity along the x -axis. Hence $\rho v = \rho \frac{F}{6\pi\eta R} = \frac{\beta^{-1}}{6\pi\eta R} \frac{\partial \rho}{\partial x} = D \frac{\partial \rho}{\partial x}$ and

$$D = \frac{\beta^{-1}}{6\pi\eta R}.$$

This is the *Sutherland–Einstein–Smoluchowski* relation characterizing the transport coefficient of diffusion and its relation with the “dissipation” η . The quantity βD should be regarded as the *susceptibility* or *response* in speed v to a force F driving the Brownian particle.

A particle starting at the origin and undergoing diffusion at time $t > 0$ will have x -coordinate randomly distributed with Gaussian distribution $f(x, t)dx = e^{-\frac{x^2}{4Dt}} \frac{dx}{\sqrt{4\pi Dt}}$, as a consequence of the diffusion equation $\frac{\partial \rho}{\partial t} = D\Delta\rho$ with initial value $\rho(x) = \delta(x)$.

Hence it will be at average square distance from the origin, in the x -direction, $r^2 = \lim_{t \rightarrow \infty} \frac{1}{t} \langle x^2(t) \rangle = 2D$: this characterizes the fluctuations of the dissipative motion with diffusion coefficient D .

On the other hand $r^2 = \lim_{t \rightarrow \infty} \frac{1}{t} \langle x^2(t) \rangle$ can also be computed by averaging $x(t)^2 = (\int_0^t u(t) dt)^2$, $u(t) \stackrel{def}{=} \dot{x}(t)$, and a brief heuristic computation shows that the average is $t \int_{-\infty}^{\infty} \langle u(0)u(t') \rangle dt'$ hence

$$D = \frac{1}{2} \int_{-\infty}^{\infty} \langle u(0)u(t) \rangle dt$$

The above two equations establish a relation between velocity fluctuations and dissipation (the latter being expressed by the diffusion coefficient D or by the related viscosity η), [6].

Patterns fluctuations, stochastic processes

Unlike the theory of errors, besides the average of the square displacement,

the theory of Brownian motion devotes attention, also to the joint fluctuation of many variables, namely to the probability that the actual path of a Brownian particle deviates from a predefined path.

More generally, given an observable X one looks at the probability that a string or *path* or *pattern* of results of observations of X , namely x_i , $i = 1, 2, \dots, T$, performed at discrete times, or $x(t)$, $0 \leq t \leq T$, performed continuously in a time interval of length T .

The discrete time case arose earlier in a work by Bachelier on stock market prices, [7], and the continuous time case begins to be studied in the theory of Einstein and Smoluchowski.

In general the probability distribution of the possible paths is called a *stochastic process*. When the successive values of the observable X are independent of each other the process is often called a *Bernoulli process*; if they are not independent but the successive variations $x_{i+k} - x_i$ or $x(t+\tau) - x(t)$ are independent random quantities, the process is called an *independent increments process*. If the process is a Bernoulli process and the variables have a Gaussian probability distribution the process is called a *white noise*.

It is also possible to consider processes in which the successive events are correlated in more general ways: all questions that can be asked for independent increments or for white noise processes can be extended to the latter more general framework and attract great interest, both theoretical and applicative, in particular when there is strong correlation over “distant” events in time.

The Wiener process: nondifferentiable paths

The position $x(t)$ of a particle in Brownian motion is a process with random independent displacements with a Gaussian distribution and zero average: this means that if at time $t + \tau$ the position is $x(t + \tau)$ then the displacement $\delta = x(t + \tau) - x(t)$ has a probability of being between in the cube $d^3\delta$ centered at δ and with side $d\delta$ given by

$$\text{probability}(\delta \in d^3\delta) = \frac{e^{-\frac{\delta^2}{4D\tau}} d^3\delta}{(4\pi D\tau)^{\frac{3}{2}}}$$

A typical property of processes in continuous time and with independent increments is that the paths $t \rightarrow x(t)$ are quite irregular as functions of t . For instance the Brownian motion paths are not differentiable with probability 1: for small τ the variation $x(t + \tau) - x(t)$ has a square with average size $2D\tau$, so that the variations have a size of order $O(\sqrt{D\tau})$.

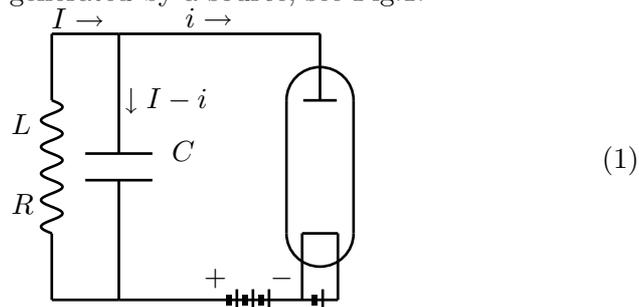
Of course this property, mathematically rigorous, can be only approximately true in the physical realizations of a Brownian motion, because by reducing the size of τ , say below some t_0 , motion eventually becomes smooth: but on time scales long compared to 1 msec , as is necessarily the case because of our human size, velocity would depend on the time interval over which it is measured and it would diverge in the limit $\tau \rightarrow 0$ or, better, it would become extremely large and fluctuating as τ approaches the time scale t_0 beyond which the theory becomes inapplicable.

Therefore, Brownian motion was an example of an actual physical realization of certain objects that had been just mathematical curiosities, like continuous *but non differentiable* curves, discovered in the '800s by mathematicians in their quest for a rigorous formulation of calculus; Perrin himself stressed this point very appropriately, [8].

The analysis of the motion at very small time scales was later performed by Ornstein and Uhlenbeck who identified the time scale t_0 with $t_0 = \lambda/m$ where λ is the friction experienced by a Brownian particle of mass m .

Schottky fluctuations

Coming back to the fluctuation-dissipation relations the *Schottky effect* theory is a prominent instance, following the theory of Brownian motions by few years only (1919). The effect is a current fluctuation in a circuit with L, R, C elements in series (i.e. with inductance L , resistance R and capacitance C), and with a diode attached in parallel to the two poles of the condenser C . The current flowing in the diode is $i_0 = ne$, where n is the average number of electrons of charge e leaving the cathode to migrate towards the anode. The current i_0 is steadily generated by a source, see Fig.1.



The circuit equation is then $L\dot{I} + RI + C^{-1}Q = 0$, $\dot{Q} = I - i(t)$, or

$$L\ddot{I} + R\dot{I} + C^{-1}(I - i(t)) = 0$$

where $i(t)$ is not equal to the average i_0 because of the discrete nature of the electron emission. Then the stationary current is

$$I(t) = \int_{-\infty}^t \frac{\omega_0^2}{\omega} e^{-(t-t')R/2L} \sin(\omega t') i(t') dt'$$

where $\omega = ((LC)^{-1} - (R/2L)^2)^{\frac{1}{2}}$ and $\omega_0 = (LC)^{-1}$. Dividing time into intervals of size τ small compared to the proper time of the circuit $2\pi/\omega_0$, the current is regarded as piecewise constant and equal to $i_k = \frac{m}{\tau}e$ with m distributed, independently over k , as a Poisson distribution with average $ne\tau$. This means that probability of m is $P(m) = e^{-n\tau} \frac{(n\tau)^m}{m!}$. Denoting by $\langle F \rangle$ the average (in time in the present case) of an observable F it is, therefore, $\langle i_k i_{k'} \rangle = i_0^2 + \delta_{kk'} \langle \frac{m^2 e^2}{\tau^2} \rangle = i_0^2 + \frac{ne^2}{\tau} \delta_{kk'}$. This implies, discretizing the integral for $I(t)$ over time intervals of size τ , that the average $\langle I(t)^2 \rangle = \frac{\omega_0^4 \tau^2}{\omega^2} \sum_{k,k'=0}^{\infty} i_k i_{k'} e^{-(k+k')\tau R/L} \sin \omega k \tau \sin \omega k' \tau$ becomes

$$\langle I(t)^2 \rangle = \frac{\omega_0^4}{\omega^2} \left(\int_0^{\infty} e^{-t'R/2L} \sin(\omega t') dt' \right)^2 i_0^2 + \frac{\omega_0^4}{\omega^2} i_0 e \int_0^{\infty} e^{-t'R/L} \sin^2 \omega t' dt'$$

which is evaluated as $i_0^2 + \frac{i_0 e \omega_0^2}{2R/L} = i_0^2 \frac{i_0 e}{2RC}$. The heat generated in the resistor, per unit time, is $R \langle I^2 \rangle = R i_0^2 + \frac{i_0 e}{2C}$. So imposing an average current i_0 it is possible to measure (by means of a thermocouple) the difference $R(\langle I^2 \rangle - i_0^2) = \frac{i_0 e}{2C}$, obtaining in this way another example of a relation between fluctuations and dissipation and, also, a scheme of a method to measure the electron charge e , (from [9]).

Johnson-Nyquist noise

Nyquist theorem provides a theoretical basis for studying of voltage fluctuations occurring in a (L, R, C) -circuit (i.e. a circuit with inductance L , resistance R and capacitance C), discovered by J.B. Johnson.

Let $E_{ch}(t)$ denote the chaotic random electromotive voltage due to the discrete nature of the electricity carriers (electrons in metals, ions in electrolytes and gases). The circuit equation is

$$L\dot{I} + RI + C^{-1}Q = E_{ch}(t), \quad \dot{Q} = I$$

Suppose that the noise has a frequency spectrum, with frequencies equispaced by d (for simplicity) and time fluctuations which is Gaussian and decorrelated i.e., denoting $\langle F \rangle$ the average of an observable F as above, $E(t)$ is a “white noise”:

$$E_{ch}(t) = d \sum_{\nu} E_{\nu} e^{i2\pi\nu t}, \quad \langle E_{\nu}(t) E_{\nu}(t') \rangle = \mathcal{E} \frac{\delta_{\nu\nu'}}{d}$$

so that $\langle E_{ch}(t) E_{ch}(t') \rangle = \mathcal{E} \delta(t - t')$. Then the current $I(t)$ is, if $\omega_0^{\pm} = -\frac{R}{2L} \pm \sqrt{\frac{1}{4}(\frac{R}{L})^2 - \frac{1}{LC}}$ and $I(0) = 0, Q(0) = 0$,

$$I(t) = \int_0^t \frac{\omega_0^+ e^{\omega_0^+(t-\tau)} - \omega_0^- e^{\omega_0^-(t-\tau)}}{\omega_0^+ - \omega_0^-} \frac{E_{ch}(\tau)}{L} d\tau.$$

By [[equipartition]] at equilibrium, the average energy is $\frac{1}{2}L \langle I(t)^2 \rangle = \frac{1}{2}k_B T$ (also equal to $\frac{1}{2}C^{-1} \langle Q^2 \rangle$) so that computing the integrals in $I(t)^2$, expressed as above and as sums over the Fourier components E_{ν} , it follows that $k_B T = L \lim_{t \rightarrow +\infty} \langle I(t)^2 \rangle = C^{-1} \lim_{t \rightarrow +\infty} \langle Q(t)^2 \rangle$ is given by $k_B T = \frac{\mathcal{E}}{2dR}$, or:

$$\frac{\mathcal{E}}{d} = 2\beta^{-1}R$$

It is now possible to evaluate the contribution $U = d \sum_{\nu} E_{\nu} e^{i2\pi\nu t}$ to the voltage “filtered” on the frequency range $[\nu', \nu'']$ (via suitable filters). This is $U_{\nu', \nu''}$ which has zero average and variance

$$\langle U_{\nu', \nu''}^2 \rangle = d^2 \sum_{\nu \in [\nu', \nu'']} |E_{\nu}|^2 = (2k_B T R)(\nu'' - \nu')$$

If Y_{ν} is the total [[*transfer admittance*]] of a circuit into which the considered L, R, C element is inserted, then the power generated in the element will be $W = \langle |d \sum_{\nu} E_{\nu} Y_{\nu} e^{2\pi i \nu t}|^2 \rangle$, hence given by

$$d \sum_{\nu} 2\beta^{-1} R |Y_{\nu}|^2 \equiv \int_0^{\infty} 4k_B T R |Y_{\nu}|^2 d\nu$$

having used the symmetry between $-\nu$ and ν to have an integral over positive ν only. The last two expressions give the fluctuation dissipation theorem of Nyquist: the ν -independence of \mathcal{E} leads to an [[*ultraviolet divergence*]] which is removed if the quantum effects at large ν are taken into account (analogously to the theory of the [[*black body radiation*]] divergence), [10].

Langevin equation

Perhaps the most well known instance of a fluctuation-dissipation relation is given by the theory of the *Langevin equation* for the motion of a particle of mass m moving in a viscous medium and subject to a chaotic, random and uncorrelated in time, force $\vec{F}_{ch}(t)$:

$$m\ddot{\vec{x}} = -\lambda\dot{\vec{x}} + \vec{F}_{ch}(t)$$

Proceeding as in the Nyquist theorem derivation and if $\langle F_{ch,i}(t)F_{ch,j}(t') \rangle = \mathcal{F}^2 \delta_{ij} \delta(t-t')$, $i, j = x, y, z$,

$$3k_B T = m \langle \dot{\vec{x}}^2 \rangle = 3k_B T = 6\mathcal{F}^2 \lambda^{-1}$$

establishing a connection between the chaotic background force and the dissipation coefficient represented by the viscosity. Considering the forced motion $m\ddot{\vec{x}} = -\lambda\dot{\vec{x}} + \vec{F}_{ext}(t)$ with $\vec{F}_{ext}(t) = \vec{F} e^{i\omega t}$ (large compared to $\vec{F}_{ch}(t)$ but still small) it follows that the averaged current induced by the periodic force is, for large t , $\langle \dot{\vec{x}} \rangle = \beta D(\omega) \vec{F}_{ext} e^{i\omega t}$ with susceptibility

$$D(\omega) = \frac{k_B T}{i m \omega + \lambda}$$

and $D(\omega)$ can be checked to be expressible also in terms of the velocity fluctuations in the equilibrium state, $\lim_{t \rightarrow \infty} \langle \dot{\vec{x}}(t+\tau) \cdot \dot{\vec{x}}(t) \rangle \stackrel{def}{=} C(\tau)$, as

$$D(\omega) = \frac{1}{3} \int_{-\infty}^{\infty} e^{-i\omega\tau} C(\tau) d\tau$$

yielding a kind of fluctuation dissipation theorem, [11, 12].

Fluctuation-Dissipation theorem

Finally consider a system in interaction with thermostats and external non conservative forces. A concrete example of such a situation (although a special case of a very general one) is in Fig.2

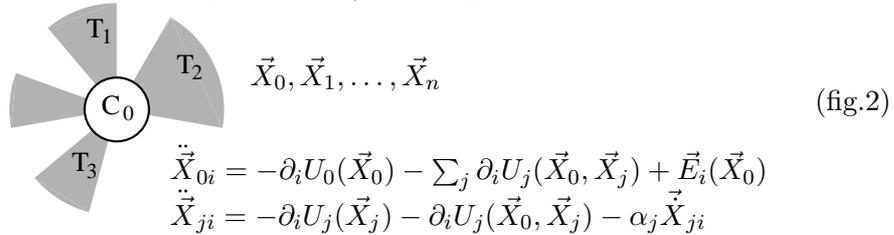


Fig.2: Here the non conservative force acts on N_0 particles at positions \vec{X}_0 in C_0 while N_j particles are at positions \vec{X}_j in the thermostats at temperatures T_j ; the potential energies $U_0(\vec{X}_0), U_j(\vec{X}_j)$ describe the interactions between the particles in C_0 or in the respective thermostats; $U_j(\vec{X}_0, \vec{X}_j)$ are the interaction potentials for the interactions between the system and the j -th thermostat, and finally $\alpha_j \vec{X}_{ji}$ are forces that keep the total kinetic energies K_j in the thermostats exactly constant

in spite of the other forces and stay equal to $K_j = \frac{1}{2}\vec{X}_j^2 = \frac{1}{2}N_jk_B T_j$; the latter condition fixes the values of the multipliers α_j in terms of $\vec{X}, \dot{\vec{X}}$. The equations of motion are written in the figure (with particles masses $m = 1$).

In all cases extra assumptions have to be made to insure that the time evolution leads to a stationary state. A special case could be as in Fig.3:

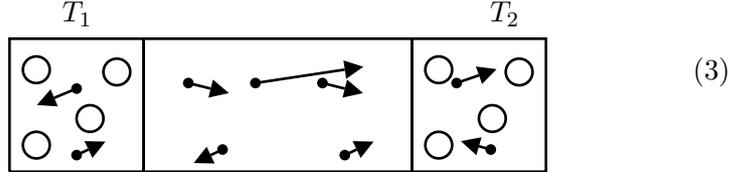


Fig.3: A thermal conduction model: the two thermostats and the intermediate box contain hard sphere particles which interact with each other with potentials $U_1(\vec{X}_1), U_0(\vec{X}_0), U_2(\vec{X}_2)$; the particles in the two thermostats are also subject to thermostating forces as in the example of Fig.1; the particles in the container interact also with the ones in the thermostats via potentials $U_1(\vec{X}_0, \vec{X}_1), U_2(\vec{X}_0, \vec{X}_2)$.

For $\vec{E} = \vec{0}$ and all thermostats at the same temperature the system admits an invariant distribution μ_0 . For $\vec{E} \neq \vec{0}$ the phase space volume measured with μ_0 will contract at a rate $-\sigma(X, \dot{X})$ which, in terms of the microscopic equations, is defined as their *divergence* (recall that if $\dot{\xi}_i = \Gamma_i(\vec{\xi})$ is a generic system of ordinary differential equations, $i = 1, \dots, n$, then its divergence is defined as the $\sum_i \frac{\partial \Gamma_i}{\partial \xi_i}(\vec{\xi})$: its value yields the variation per unit time of the volume of an infinitesimal volume element $d\vec{\xi}$ around $\vec{\xi}$) changed in sign, and therefore depends on the $6N$ phase space coordinates $(\vec{X}, \dot{\vec{X}})$. In the case of the model in the figure the divergence turns out to be, for large numbers of particles, $\sigma(\vec{X}, \dot{\vec{X}}) = \sum_{j>0} \frac{Q_j}{k_B T_j}$ if the external forces vanish (hence there is just steady heat flow) up to terms with 0 time average and if Q_j is the heat ceded by the system to the thermostats (which in this case is equal he work done by the system on the j -th thermostat per unit time).

The $\sigma(X, \dot{X}; \vec{E})$ vanishes for $\vec{E} = \vec{0}$, and $T_1 - T_j = 0$, because μ_0 is invariant (this holds if the metric on phase space is suitably chosen, but if not it differs from 0 by a term with zero average and zero average fluctuations, which do not affect the analysis).

The distribution μ_0 is important because, if it is *ergodic* as it is often implicitly supposed, it allows to express the time averages as *phase space averages* with probability 1 with respect to initial data randomly chosen with respect to μ_0

The physical interpretation of σ is of *entropy production rate* in the mo-

tion starting from a microscopic configuration typical of the distribution μ_0 (i.e. randomly selected with a probability distribution μ_0): it establishes a “conjugation” between “forces” \vec{E} (include, henceforth, the temperature differences $T_1 - T_j$ among the E ’s for uniformity of notation) and “fluxes” \vec{J} via

$$J_i(X, \dot{X}; \vec{E}) = \frac{\partial \sigma(X, \dot{X}; \vec{E})}{\partial E_i}.$$

Let $S_t^{\vec{E}}$ denote the solution flow of the equations of motion, associating with a generic initial datum (X, \dot{X}) the datum $S_t^{\vec{E}}(X, \dot{X})$ into which it evolves in time t . Then for $\vec{E} \neq \vec{0}$ the system evolves in time reaching a stationary state in which any observable Φ has a (phase space) average (hence a time average) that can be defined by $\langle \Phi \rangle = \lim_{t \rightarrow \infty} \mu_0(S_t^{\vec{E}} \Phi)$. Then setting $\Phi = J_i(X, \dot{X}; \vec{E})$ and $J_i(\vec{E}) = \langle J_i(X, \dot{X}; \vec{E}) \rangle$, it follows

$$J_i(\vec{E}) = \int_0^\infty dt \frac{d}{dt} \int \mu_0(dX d\dot{X}) J_i(S_t^{\vec{E}}(X, \dot{X}); \vec{E})$$

and using the definition of phase space contraction it is possible, [13], to check the exact relation:

$$J_i(\vec{E}) = \int_0^\infty \sigma(S_{-t}^{\vec{E}}(X, \dot{X}); \vec{E}) J_i(X, \dot{X}; \vec{E}) \mu_0(dX d\dot{X})$$

Therefore, the susceptibilities $L_{ij} = \left. \frac{\partial J_i(\vec{E})}{\partial E_j} \right|_{\vec{E}=\vec{0}}$ are (using that $\sigma|_{\vec{E}=\vec{0}} = 0$ and ignoring the difficult discussion of the interchanges of limits, derivatives and integrals)

$$L_{ij} = \int_0^\infty dt \langle J_j(X, \dot{X}; \vec{0}) J_i(S_t^{\vec{0}}(X, \dot{X}); \vec{0}) \rangle_{\vec{E}=\vec{0}}$$

where the average is with respect to the equilibrium distribution μ_0 . This shows that the fluctuation-dissipation theorem can be formulated as “*knowledge of the correlation completely determines the susceptibility*”.

The latter expression, known as *Green-Kubo formula* also shows the *Onsager reciprocity*, $L_{ij} = L_{ji}$ which holds under the assumption that the time evolution is reversible, i.e. that there exists a map \mathcal{I} of phase space with $\mathcal{I}^2 = \text{identity}$, which anticommutes with the time evolution $\mathcal{I} S_t^{\vec{0}} = S_{-t}^{\vec{0}} \mathcal{I}$ and which leaves μ_0 invariant ($\mu_0 \circ \mathcal{I} = \mu_0$), [12].

If time reversibility also holds for $\vec{E} \neq \vec{0}$, as it is often the case, the fluctuation dissipation theorem can also be shown to be generalized by the [*fluctuation theorem*]], [14].

The exchange of limits involved in the derivation of the fluctuation-dissipation theorem can be completely discussed under the extra [[*chaotic hypothesis*]], [15, 16]. or even on weaker and earlier versions of it, [17]. However it has to be kept in mind that even in this case the proof only states a property of the susceptibilities "at zero forcing": "per se" this does not even imply that the fluctuation theorem is observable as checking it requires measuring currents at small "but non zero" forcing (because no current flows at zero forcing). No good estimates are available in the few concrete cases in which a proof is possible and in the literature doubts have been raised about the physical relevance of the above derivation of the fluctuation-dissipation theorem: of course no one doubts of the validity of the reciprocity relations (and linear response) but of the correctness of their explanation. It might even be that the susceptibility at positive non zero (small) field is not a smooth function of the field which can only be interpolated better and better as the field tends to zero. See [18].

Blue of the sky

The fluctuation-dissipation theorem has many more applications: it is worth mentioning an explanation of the color of the sky via [[*Rayleigh diffusion*]]. If light of frequency $\nu = \omega/2\pi$ arrives into a gas medium it is diffused and the power diffused is a fraction depending on the frequency or on the wavelength as $W \propto \omega^4 = \lambda^{-4}$ (more precisely $W = \frac{2}{3} \frac{e^2}{c^3} \omega^4 \left(\frac{e}{m(\omega^2 - \omega_0^2)} \right)^2$ if $\omega_0/2\pi$ is the frequency of the external electronic orbit of the molecules). Hence $\frac{W_{blue}}{W_{red}} = \left(\frac{4.5 \cdot 10^4 \text{ \AA}^o}{6.5 \cdot 10^4 \text{ \AA}^o} \right)^4 \sim 4.3$. So much more blue light is scattered, or more properly absorbed and emitted in a spherically symmetric way.

A light wave hitting a region of the wavelength size in air will simultaneously excite many atoms at a given time, but the phase of the electric field will be different. If n_1, n_2 denote the number of atoms (large, for air in normal conditions) actually present in two such adjacent regions of half wavelength size. Then the electric (or magnetic) field seen by an observer is $\sim n_1 E_1 + n_2 E_2 = (n_1 - n_2) E_1$ which has 0 average. However the scattered power is proportional to the average of the square $\langle (n_1 - n_2)^2 \rangle = \langle n_1 \rangle + \langle n_2 \rangle$ because the numbers of atoms is Poisson distributed, so that the intensity of the diffused light is proportional to the single atom diffusion I_1 times $(\langle n_1 \rangle + \langle n_2 \rangle)$ and the destructive interference is not complete: hence blue light dominates in the color of the sky, [19].

Correlated fluctuations

The fluctuations due to uncorrelated events discussed so far have quite different properties compared to the fluctuations of correlated events. The subject is very wide and arises in studying processes describing paths in time (continuous or discrete) as well as processes in which the events are labeled by labels with different physical meaning. For instance the events could be associated with the place in space where they develop: so x_ξ could be events labeled by lattice sites in a d -dimensional lattice Z^d . Or they could be labeled by $\xi \in R^d$ when they happen at the positions of a continuum d -dimensional space. The latter examples are called “stochastic fields” and cover also the already considered processes in time because time can be regarded as just one more coordinate.

A paradigmatic example is the field σ_ξ where the event σ_ξ is the value of a spin located at the site $\xi \in Z^d$. There are many probability distributions that can be considered on such field and it is convenient to restrict attention to translation invariant probability distributions. The latter are distributions which attribute the same probability to the event in which the values $\sigma_1, \dots, \sigma_n$ of the field occur at sites ξ_1, \dots, ξ_n or at the translated sites $\xi_1 + x, \dots, \xi_n + x$, $x \in Z^d$.

The translation invariant distributions are a natural generalization of the independent distributions or of the independent increments distributions. Similar questions can be raised about them: for instance, given a cube $\Lambda \subset Z^d$ with $|\Lambda|$ lattice points, it is interesting to study the probability of $\sum_{\xi \in \Lambda} \sigma_\xi \in [\sqrt{|\Lambda|} a, \sqrt{|\Lambda|} b]$ i.e., physically interpreted as *magnetization*.

The latter quantity might be expected to be a Gaussian, as in the case of independent variables. However already in the simple cases in which the probability of a value $\sigma_\xi = \pm 1$ at ξ , given the other field values, depends just on the field values in the nearest neighbor sites, the *[[Ising model]]*, it is possible (although exceptional) that the quantity $s \stackrel{def}{=} |\Lambda|^{-\frac{1}{\alpha}} \sum_{\xi \in \Lambda} \sigma_\xi$ not only does not have a Gaussian distribution in the limit $|\Lambda| \rightarrow \infty$ but it is not trivial only if α is suitably chosen ($\alpha = \frac{8}{7}$ if the lattice dimension is $d = 2$) and different from $\alpha = 2$. This is the *critical fluctuations* phenomenon which is of great importance in statistical mechanics and in the theory of phase transitions but which would lead us too far in the present context, [16].

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Recommended reading

- J. Perrin, see above reference
- B. Duplantier, see above reference
- A. Pais, see above reference
- G. Gallavotti, Ch. 8 of Statistical Mechanics